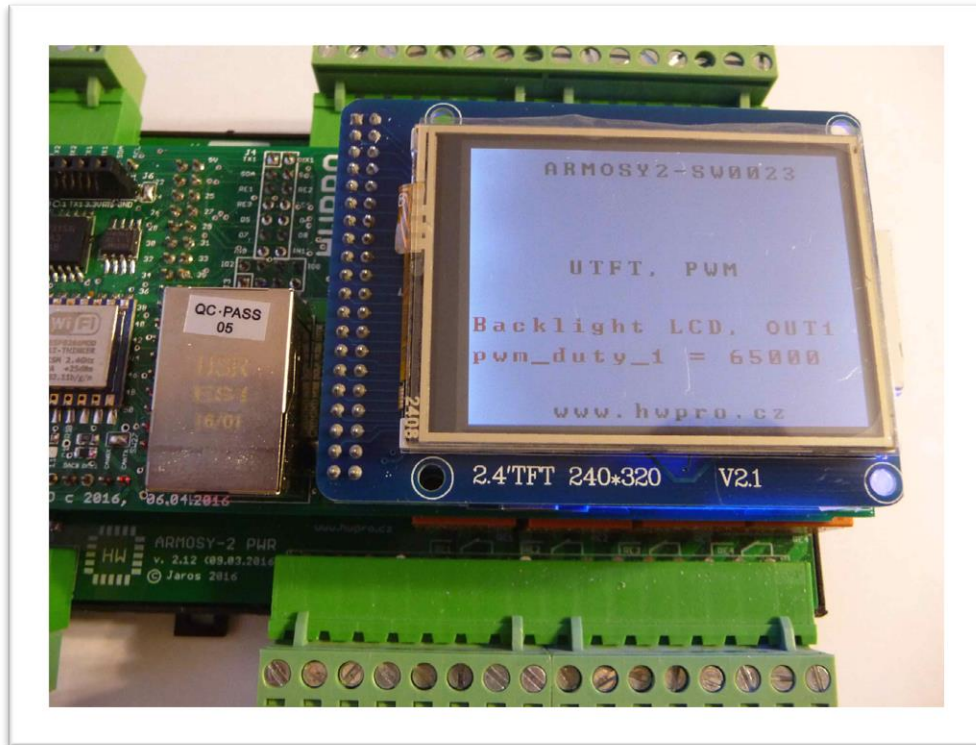


Example – SW0023

PWM 2Hz-40kHz, OUT1-4, Backlight LCD



Universal Control System		ARMOSY-2			ARduino MOdule SYstem	
<p>ARM, 32 bit 84MHz, 512k FLASH</p>	<p>Arduino DUE 3.3V Technology</p>	<p>EEPROM, I2C 256 kB</p>	<p>RTC, DS3231, I2C temper.compensation Battery CR2032</p>	<p>SD CARD, SPI Slot In TFT LCD</p>	<p>2.4" COLOR LCD 240x320 px</p>	<p>OPTION NF amplifier, DAC Audio</p>
<p>2x</p> <p>RS-232</p> <p>115 kbps</p>	<p>Two Wire</p> <p>RS-485</p> <p>115 kbps</p>	<p>OPTION</p> <p>Mini USB, FTB232</p> <p>USB</p> <p>1 Mbps</p>	<p>OPTION</p> <p>ESP8266, UART</p> <p>WiFi</p> <p>2 Mbps</p>	<p>OPTION</p> <p>W5500, SPI</p> <p>Ethernet</p> <p>10/100 Mb, 2 LED</p>	<p>OPTION</p> <p>GSM, UART</p> <p>GSM</p> <p>SIM800L</p>	<p>Two I2C BUS</p> <p>1-wire BUS DALLAS</p> <p>1Wire BUS</p>
<p>8x</p> <p>INPUT</p> <p>Optocoupler 6 MODE</p>	<p>8x</p> <p>OUTPUT</p> <p>Optocoupler 3 MODE, PWM</p>	<p>8x</p> <p>IN / OUT</p> <p>Universal I/O Direct CPU</p>	<p>OPTION</p> <p>2x</p> <p>0 – 30A</p> <p>Current measurement</p>	<p>OPTION</p> <p>4x AD</p> <p>0 – 10V</p> <p>18b AD Converter</p>	<p>OPTION</p> <p>4x DA</p> <p>0 – 10V</p> <p>12b DA Converter</p>	<p>OPTION</p> <p>4x</p> <p>10A, 250V, AC</p>
<p>POWER INPUT</p> <p>8V ~ 72V, 3W</p> <p>AC, DC, USB</p>	<p>Measurement System Voltage</p> <p>3.3V / 5V</p>	<p>OTHERS</p> <p>2x Buttons 2 x LED Buzzer</p>	<p>User Design PCB</p> <p>Size 10x4 cm</p>	<p>DIN</p> <p>OPTION</p> <p>12 modul</p>	<p>Programming</p> <p>Free Software</p>	<p>CZ, EN</p> <p>User manual Examples</p>


```

// MAIN PWM INITIALIZATION
//-----
void pwm_setup( uint32_t pwm_pin, uint32_t pwm_freq, int iclock )
{
    uint32_t pwm_duty = 0;
    uint32_t chan = g_APinDescription[pwm_pin].ulPWMChannel;

    // SET CLOCK FREQUENCY
    //-----
    if (iclock==1) pwm_set_clockA_freq( pwm_max_duty_Ncount*pwm_freq );
    if (iclock==2) pwm_set_clockB_freq( pwm_max_duty_Ncount*pwm_freq );

    if (pwm_pin>=6 && pwm_pin<=9)
    {
        // SET PWM RESOLUTION
        //-----
        pwm_duty = mapResolution( pwm_duty, pwm_resolution_nbit, PWM_RESOLUTION);

        // PWM STARTUP AND SETUP CLOCK
        //-----
        pmc_enable_periph_clk( PWM_INTERFACE_ID );
        PWMC_ConfigureClocks( pwm_clockA_freq, pwm_clockB_freq, VARIANT_MCK );

        // SETUP PWM FOR pwm_pin
        //-----
        PIO_Configure(
g_APinDescription[pwm_pin].pPort, g_APinDescription[pwm_pin].ulPinType, g_APinDescription[pwm
_pin].ulPin, g_APinDescription[pwm_pin].ulPinConfiguration);
        if (iclock==1) PWMC_ConfigureChannel(PWM_INTERFACE, chan, PWM_CMR_CPRES_CLKA, 0, 0);
        if (iclock==2) PWMC_ConfigureChannel(PWM_INTERFACE, chan, PWM_CMR_CPRES_CLKB, 0, 0);
        PWMC_SetPeriod(PWM_INTERFACE, chan, pwm_max_duty_Ncount);
        PWMC_SetDutyCycle(PWM_INTERFACE, chan, pwm_duty);
        PWMC_EnableChannel(PWM_INTERFACE, chan);
    }
}

// WRITE DUTY CYCLE
//-----
void pwm_write_duty( uint32_t pwm_pin, uint32_t pwm_duty )
{
    if (pwm_pin>=6 && pwm_pin<=9)
    {
        pwm_duty = mapResolution( pwm_duty, pwm_resolution_nbit, PWM_RESOLUTION);
        uint32_t chan = g_APinDescription[pwm_pin].ulPWMChannel;
        PWMC_SetDutyCycle(PWM_INTERFACE, chan, pwm_duty);
    }
};

// FORCE PWM STOP
//-----
void pwm_stop( uint32_t pwm_pin )
{
    pinMode(pwm_pin, OUTPUT); // sets the digital pin as output
    digitalWrite(pwm_pin, LOW); // sets the LED off
};

#endif

```

1.

```

30 ARMOZY_SW0023_2 | Arduino 1.6.5
Soubor Úpravy Projekt Nástroje nápověda
ARMOSY_SW0023_2 PWM
40 #include <Arduino.h> // Arduino Core Library
24 extern uint8_t SmallFont[]; // Type Font Small
25 extern uint8_t BigFont[]; // Type Font Big
26 byte OUT_1 = 6; // HW pin OUT1
27
28 // ***** SETUP *****
29
30 void setup()
31 {
32
33 // ■ TFT
34
35 myGLCD.InitLCD(); // Initialization LCD
36 myGLCD.clrScr(); // Clear Screen
37 myGLCD.fillScr(VGA_WHITE); // VGA Background Transparency
38 myGLCD.setColor(0, 0, 0); // Fond Black Colors (R, G, B) BLACK
39 myGLCD.setBackColor(255, 255, 255); // White Background
40 myGLCD.setFont(BigFont); // Settings Size Fonts
41 myGLCD.print("UIFI, PWM", 80, 100); // Text, position x, position y
42 myGLCD.setColor(255, 0, 0); // Fond Black Colors (R, G, B) RED
43 myGLCD.print("Backlight LCD, OUT1", 0, 150); // Text, position x, position y
44 myGLCD.setColor(0, 0, 0); // Fond Black Colors (R, G, B) BLACK
45 myGLCD.print("ARMOZY2-SW0023", 60, 10);
46 myGLCD.print("www.hwpro.cz", CENTER, 220);
47
48 // ■ I/O
49 pinMode(OUT_1, OUTPUT);
50
51 // ■ PWM setup
52 pwm_set_resolution(16); // pwm resolution (16 bit, 8bit)
53 uint32_t pwm_duty_1 = 65000; // duty (Backlight LCD value 65535 min, 1 max.)
54 uint32_t pwm_freq_1 = 100; // frequency Hz
55 pwm_setup(OUT_1, pwm_freq_1, 1); // pwm_setup (pin, freq, iclock 2 ist Clock B)
56 pwm_write_duty(OUT_1, pwm_duty_1); // pin, duty_cycle_pro_phase
57
58 }
59
60
61 // ***** MAIN *****
62
63 void loop()
64 {
65 {
66 }
67 }
68
    
```

2.

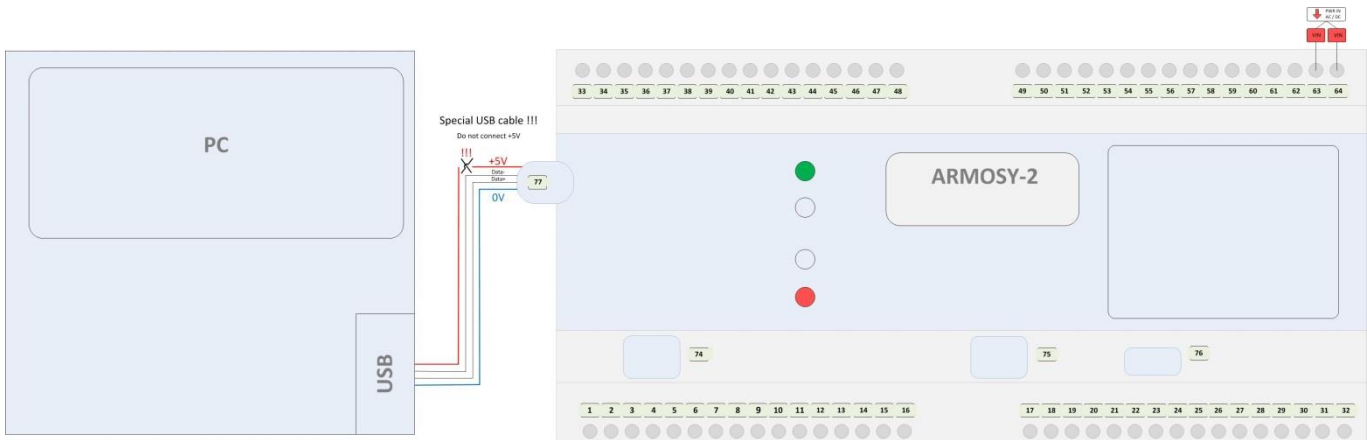
```


50 void pwm_set_clockB_freq(uint32_t val)
51 {
    
```

3.

```

30 ARMOZY_SW0023_2 | Arduino 1.6.5
Soubor Úpravy Projekt Nástroje nápověda
ARMOSY_SW0023_2 PWM
1 // ***** PWM LIB *****
2
3 /*
4
5 Library: pwm01.h (version 01)
6 Date: 2/11/2013
7 Written By: randomvibe
8 Free Download: https://github.com/it-workshop/pwm01.h_by_randomvibe/blob/master/PWM01.pwm01.cpp
9
10 Purpose:
11 Setup one or two unique PWM frequencies directly in sketch program,
12 set PWM duty cycle, and stop PWM function.
13
14 User Functions:
15 pwm_set_resolution(int res) - setup PWM resolution: up to 16 bit
16 pwm_setup( uint32_t pwm_pin, uint32_t pwm_freq, int iclock) - Setup PWM on clock-A (iclock=1) or clock-B (iclock=2)
17 pwm_write_duty( uint32_t pwm_pin, uint32_t pwm_duty) - Write PWM duty cycle
18 pwm_stop( uint32_t pwm_pin) - Force PWM stop
19
20 Notes:
21 - Applies to Arduino-Due board, PWM pins 6, 7, 8 & 9.
22 - Library Does not operate on the I/O pins.
23 - Unique frequencies set via PWM Clock-A ("CLKA") and Clock-B ("CLKB")
24 Therefore, up to two unique frequencies allowed.
25 - Set max duty cycle counts (pwm_max_duty_hcount) equal to 255 per Arduino approach. This value is best SUITED for low frequency
26 applications (2Hz to 40,000Hz) such as PWM motor drivers, 38kHz infrared transmitters, etc.
27 - Future library versions will address high frequency applications.
28 - Arduino's "wiring_analog.c" function was very helpful in this effort.
29
30 */
31
32 #ifndef _arm_
33 #include "pwm01.h"
34
35 int pwm_resolution_nbit = 16;
36 uint32_t pwm_clockA_freq = 0;
37 uint32_t pwm_clockB_freq = 0;
38 uint32_t pwm_max_duty_hcount = 255;
39
40 void pwm_set_resolution(int res)
41 {
42 pwm_resolution_nbit = res;
43 }
44
45 void pwm_set_clockA_freq(uint32_t val)
    
```





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